

# MOTOMAN MPX1150

Small Robot optimized for Painting



The compact MOTOMAN MPX1150 robot was developed especially for painting of small work pieces. It provides a payload of 5 kg for mounting multiple guns and small bells. Its high density layout saves space by reducing the size of the painting booth. The S/L axis is designed with no offset to enable installation of the manipulator closer to a work piece. The robot can be mounted on the floor, wall or ceiling and has three selectable access points for power cables.

The MOTOMAN MX1150 is controlled by the highperformance MOTOMAN DX200 controller, which is available with optional Functional Safety Unit (FSU) that offers a wide range of new safety functions.

### **KEY BENEFITS**

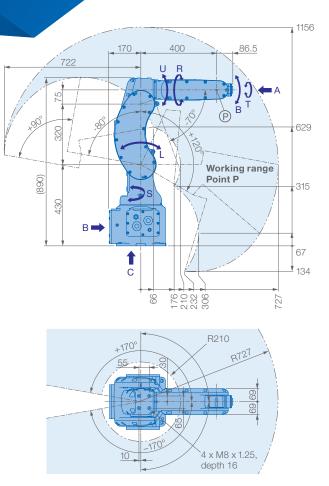
- High painting quality
  - 5 kg payload
- Mounting of multiple guns and small bells
- Optimized range of motion
  - $\ensuremath{\mathsf{S/L}}\xspace$  axis designed with no offset for
  - Effective use of area under the arm and
    Closer installation of the robot arm to a work piece
- Compact & flexible installation
  - Minimized dimensions and interference radius enable high-density layout
  - Flexible layout due to floor, ceiling or wall mounting
  - Three selectable access points for power cables



## **MOTOMAN MPX1150**

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Ζ (300)



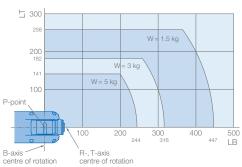
Allowable wrist load

# τüν

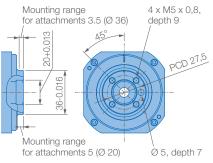
X



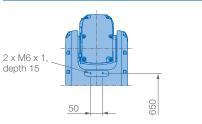




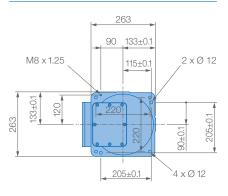
View A



View B



View C



Mounting options: Floor, ceiling, wall Protection class: IP4X/65

Specifications MPX1150						
Axes	Maximum motion range [°]	Maximum speed [m/sec.]	Allowable moment [Nm]	Allowable moment of inertia [kg · m²]	Controlled axes	6
					Max. payload [kg]	5
S	±170 (Wall ±90)	1.5	-	-	Repeatability [mm]	±0.02
L	+120/-80		-	-	Max. working range R [mm]	727
U	+90/-70		-	-	Temperature [°C]	0 to +40
R	±190		12	0.3	Humidity [%]	20 - 80
В	±135		12	0.3	Weight [kg]	57
т	±360		7	0.1	Power supply, average [KVA]	1.0

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All dimensions in mm. Technical data may be subject to change without previous notice. Please request detailed drawings at robotics@yaskawa.eu.com.